

Curriculum Vitae Ivan Virgala

# PERSONAL INFORMATION

# Ivan Virgala



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Sex | Date of birth | Nationality

### **WORK EXPERIENCE**

June 2024 - present

#### **Full Professor**

Technical University of Košice / Faculty of mechanical engineering / Letná 9, 042 00 Košice, Slovakia

Research and pedagogical activity

### June 2017 - May 2024

### **Associate Professor**

Technical University of Košice / Faculty of mechanical engineering / Letná 9, 042 00 Košice, Slovakia

Research and pedagogical activity

### October 2012 - May 2017

### Researcher

Technical University of Košice / Faculty of mechanical engineering / Letná 9, 042 00 Košice, Slovakia

Research and pedagogical activity

### **EDUCATION AND TRAINING**

### 31/08/2009 - 27/08/2012

## Philosophiae doctor (PhD.)

Technical University of Košice / Faculty of mechanical engineering / Letná 9, 042 00 Košice, Slovakia

# 31/08/2004 - 31/05/2009

# Mechanical Engineer (Ing.)

Technical University of Košice / Faculty of mechanical engineering / Letná 9, 042 00 Košice, Slovakia

## PERSONAL SKILLS

Mother tongue(s)

Slovak

# Other language(s)

UNDERSTANDING		SPEAKING		WRITING
Listening	Reading	Spoken interaction	Spoken production	
B2	B2	B2	B2	B2
A1	A1	A1	A1	A1

English German

Digital competence

- MS office, Automation studio, Atmel studio, PyBullet, CoppeliaSim, SolidWorks, MATLAB/SimScape
- Programming: Python, Java, C, C++, MATLAB, Structured text, Ladder diagram, HTML, CSS
- **Driving licence**
- B



# Publications

- Mathematical framework for snake robot motion in a confined space, Applied Mathematical Modelling (2024), Elsevier Ltd.
- Sensing of continuum robots: A review, Sensors (2024), MDPI.
- A snake robot for locomotion in a pipe using trapezium-like travelling wave, Mechanism and Machine Theory (2021), Elsevier Ltd.
- Investigation of Snake Robot Locomotion Possibilities in a Pipe, Symmetry (2020), MDPI.
- A novel approach for a inverse kinematics solution of a redundant manipulator, Applied Sciences (2018), MPDI.
- An inspection of pipe by snake robot, International Journal of Advanced Robotic Systems (2016), Sage

#### **Projects**

- 008TUKE-4/2024 Implementation of machine learning methods in the teaching of industrial automation and robotics (Principal investigator)
- VEGA 1/0436/22 Research and development of modeling methods and control algorithms kinematically redundant mechanisms (Principal investigator)
- KEGA 030TUKE-4/2020 Transfer of knowledge from the field of industrial automation and robotics for teaching in the field of Mechatronics (Principal investigator)
- VEGA 1/0389/18 Research and development of kinematically redundant mechanisms (Principal investigator)
- SjF TUKE grant project: Design and implementation of a pneumatic handling arm (Principal investigator)
- Tatra bank grant project: ARMatic development of redundant robotic arm control algorithms (Principal investigator)
- Tatra bank grant project: DidacticBot Innovation of the teaching process of robotics and mechatronics (Principal investigator)
- Tatra bank grant project: TransBridge inovatívne metódy v navrhovaní robotických mechanizmov (Principal investigator)
- Tatra bank grant project: LocoSnake Motion of robotic mechanisms supported by control software (Principal investigator)
- KEGA 030TUKE-4/202 Transfer poznatkov z oblasti priemyselnej automatizácie a robotiky do výučby v odbore Mechatronika (Principal investigator)

### **Patents**

- Alloy-based pipe machine with shape memory, Patent No. 288868 (2021)
- Test equipment for testing actuators, Patent No. 288769 (2020)
- Inertia Stepper Pipe Cleaning Machine, Patent No. 288807 (2020)
- Adaptable linear magnetic displacement sensor, Patent No. 288784 (2020)
- Wheeled pipe machine with automatic wheel span adjustment according to pipe diameter, Patent No. 288789 (2020)
- Pneumatic wrist joint of handling equipment, Patent No. 288691 (2019)
- Inspection pipe robot, Patent No. 288718 (2019)
- Linear solenoid electromagnetic actuator with differential series connected windings and permanent magnet, Patent No. 288550 (2018)

#### Honours and awards

- Rector's prize for publishing activity in the category "scientific article" published in 2021 (2021)
- Prize for the EMA thematic exhibition at the international engineering fair in Nitra 2016: Pipe inspection robot (2016)
- 2nd place at the international robotics competition "Robotic Day 2013" in Prague in the mini sumo robot category (2013)
- 2nd place in the faculty round of student scientific professional activity (2009)
- Awarded by the Dean of the Faculty of Engineering with the "Outstanding Student" medal (2009)

### Memberships

- Applied Sciences (WoS) Review board
- Sensors (WoS) Topic board
- Frontiers in Robotics and AI (WoS) Associate Editor

### Databases and digital identifiers

- Web of Science: Researcher ID: AAH-6825-2019, H-index: 12, Publications: 60, Sum of Times Cited: 503
- Scopus: Researcher ID: 43862003700, H-index: 14, Publications: 80, Sum of Times Cited: 746
- Google scholar: H-index: 19, Sum of Times Cited: 1587